

# LidarView Presentation - IGN

2023-06-29 G.Ferret

# Summary

- Kitware quick overview
- Overview of VTK / ParaView
- LidarView : A Paraview Based App
- ParaView/ LidarView for distributed applications
- Potential applications to aerial lidar data

# Kitware quick overview



# Kitware / Leader in AI & scientific open source solutions

## Software development

Based on open source tools  
300+ active projects worldwide



## Sustained Growth

Since creation of the company  
100% employee-owned



## 230 employees Worldwide

6 offices across USA/Europe



## Most staff with PhD or Master

High Level customer expertise



## 25 years of expertise

Kitware USA, 1998  
Kitware Europe, 2010

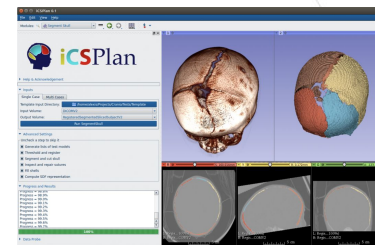
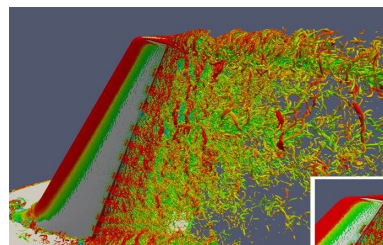
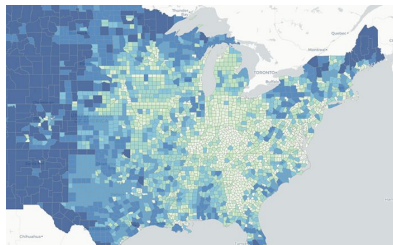
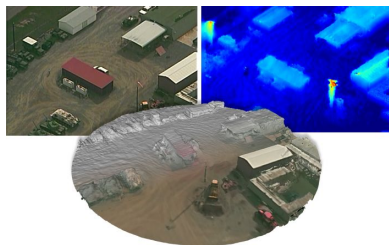


## Revenue 2020

\$39M consolidated



# Areas of expertise / Built on open source



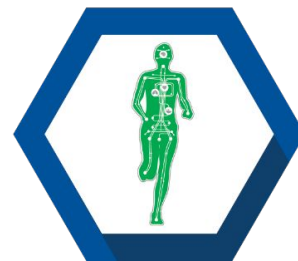
Computer Vision



Data and Analytics



Scientific Computing

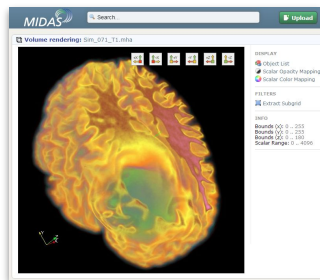


Medical Computing

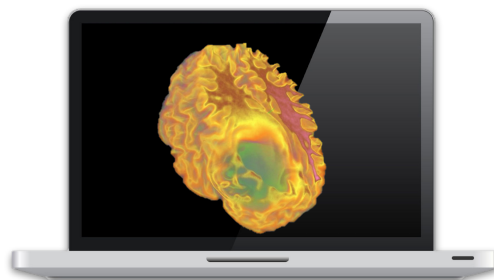


Software Solutions

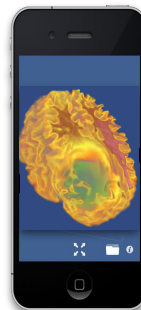
# Applications / Universal Platforms



Web



Desktop



Mobile



Cloud /HPC

kitware  
Platforms



3D Slicer



KWIVER



mstk

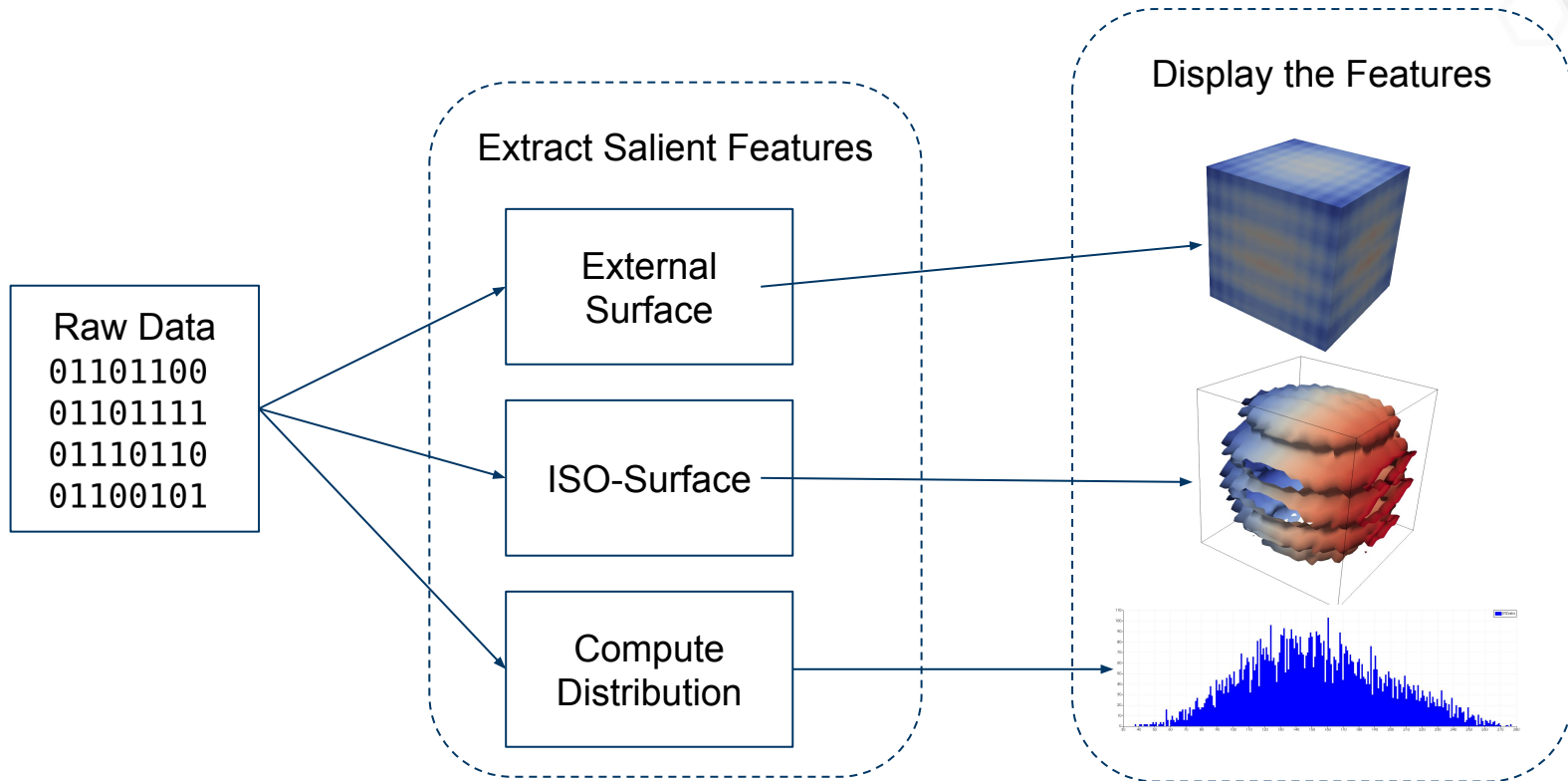




# Overview of VTK / ParaView



# Scientific Visualization Basics

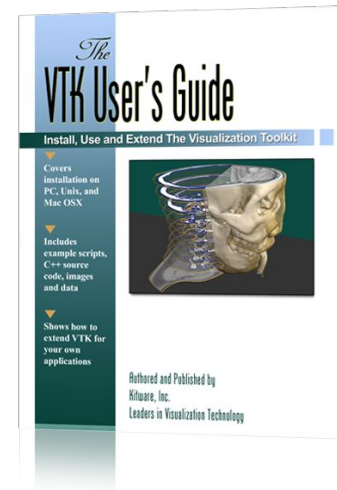
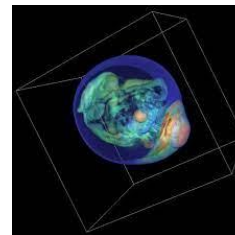
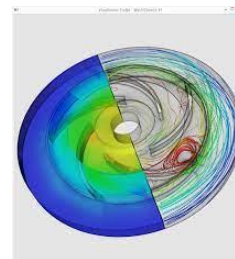




# VTK / Cross-Platform Visualization Toolkit (1993)

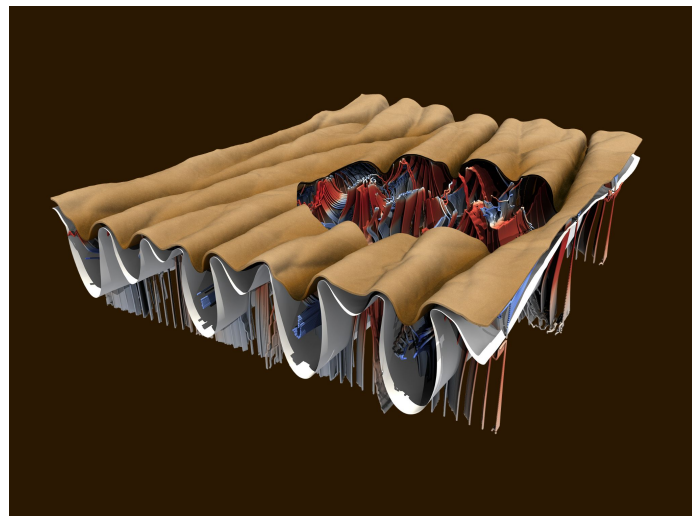
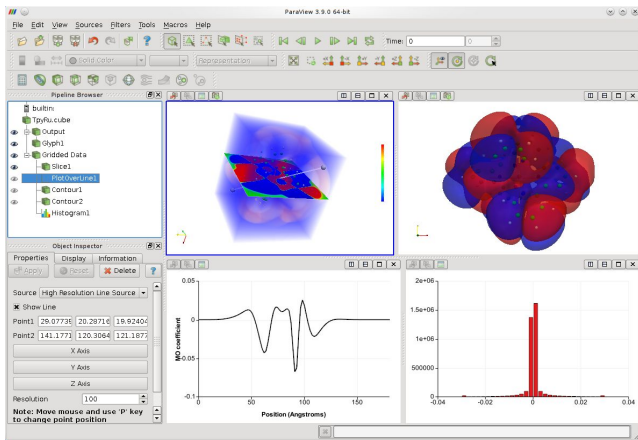
- Open-source (BSD-3 licence), freely available, cross-platform toolkit for post-processing and visualization of scientific data

# VTK



# ParaView / High-Performance Post-Processing (2002)

- Open-source, multi-platform, data analysis and visualization application
- Analysis of extremely large datasets using distributed memory computing resources

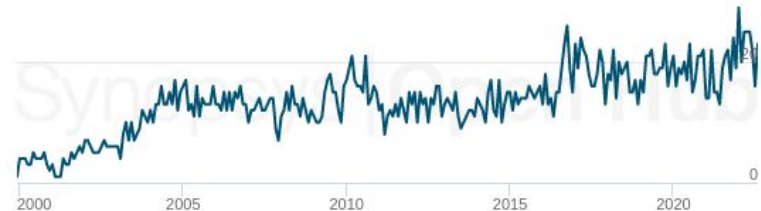


# ParaView Community

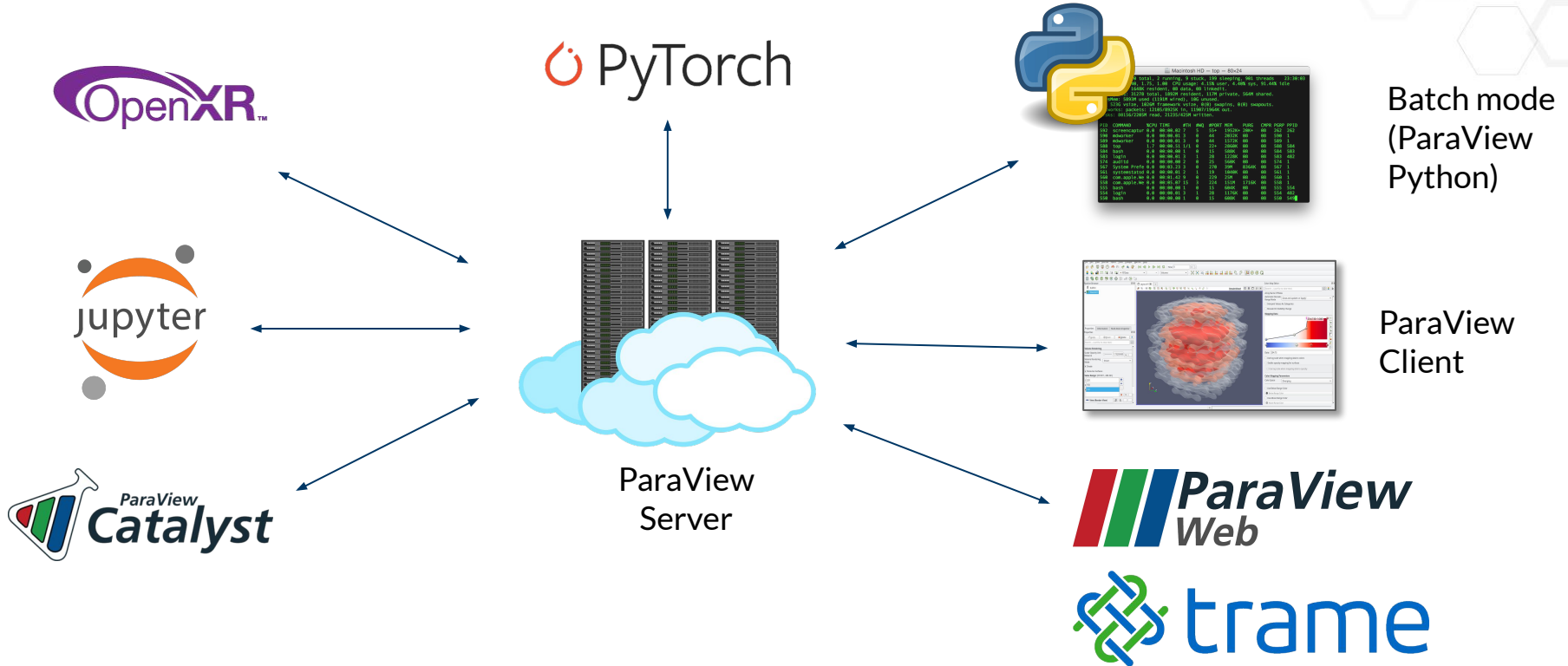
- Open Source Software (BSD license)
- Run on most of Top500 HPC
- 300000+ download yearly from Kitware servers
  - More users via other unknown download channel (Linux packaging, Enterprise distribution...)
- 157k commits made by 339 contributors since 2000
- 1.6M lines of code



Contributors per Month



# ParaView Ecosystem

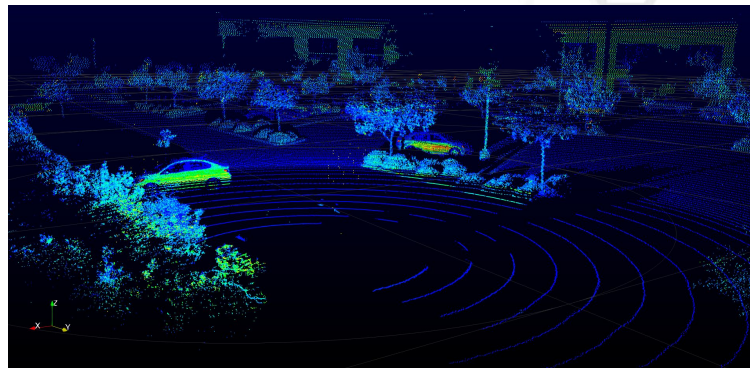


# LidarView : A Paraview based app



# LidarView A Visualization and Analytics Toolkit

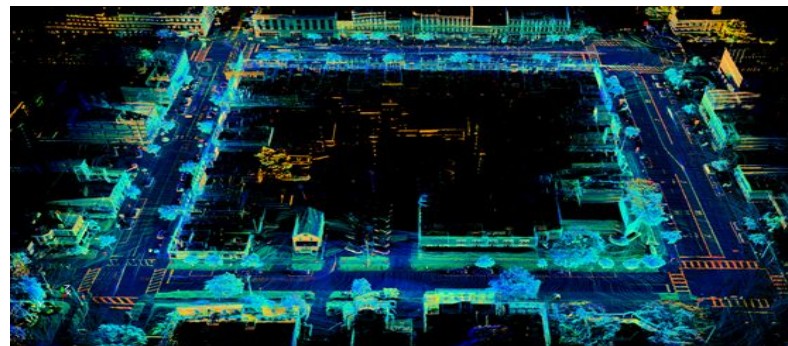
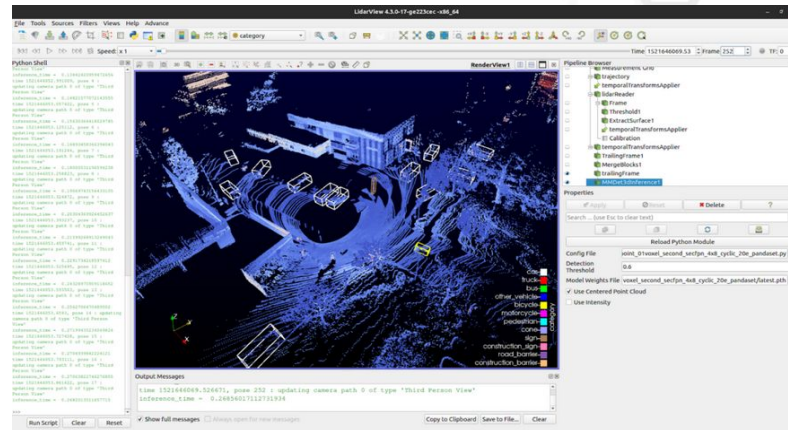
- Easy to use ParaView-based application with a Graphical User Interface (GUI)
- Real-time open source software to visualize, record and perform analysis of LiDAR data
  - Extensible/Adaptable to Support Various LiDAR and enables vendor specific apps
- Also Allows opening las files (since V4.4.0)
- Continuously evolving toolkit to enhance and improve upon vendor interface, analytics and automation
- VR available for visualization and interaction
- Developed LidarView based applications for LiDAR vendors
- Permissive Open Source Licensing





# LidarView : Point Cloud processing Capabilities

- SLAM :
  - Enables trajectory estimation and map reconstruction from it
  - Fuses external sensors (IMU,GPS, Wheel Odometer, Camera...) for more robustness, accuracy and point colorization
- Deep Learning
  - Enables usage of DL libraries such as PyTorch, TensorFlow or MMDetection3D toolkit for Deep Learning applications
- Ongoing : Embedding most useful PCL functionalities as filters
- Anything you can think of (on temporal or static data), through Python or C++ implementation thanks for modular interfacing
- Can be done at big scale thanks for Paraview distributed computing capabilities



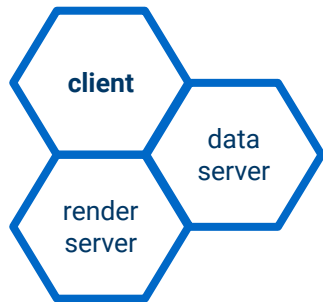
# ParaView / LidarView for Distributed computation



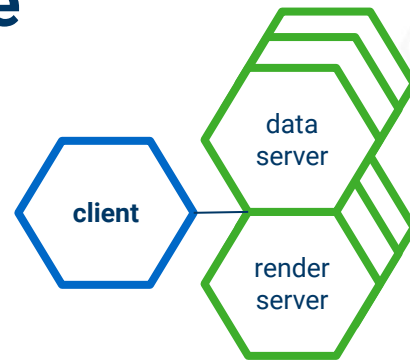


# ParaView's Client Server Architecture

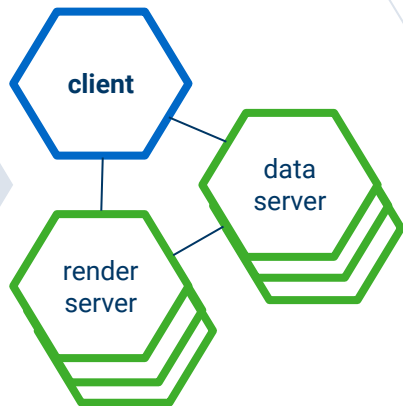
Built-in  
paraview



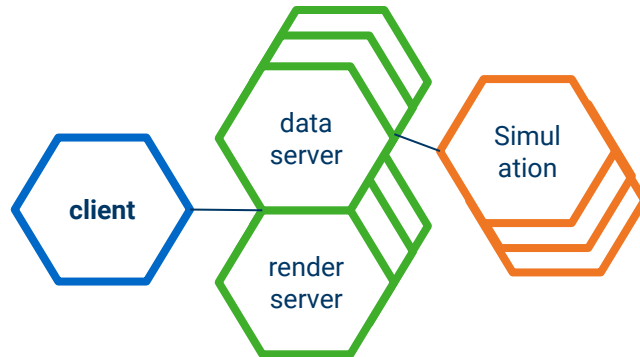
Distributed  
pvserver



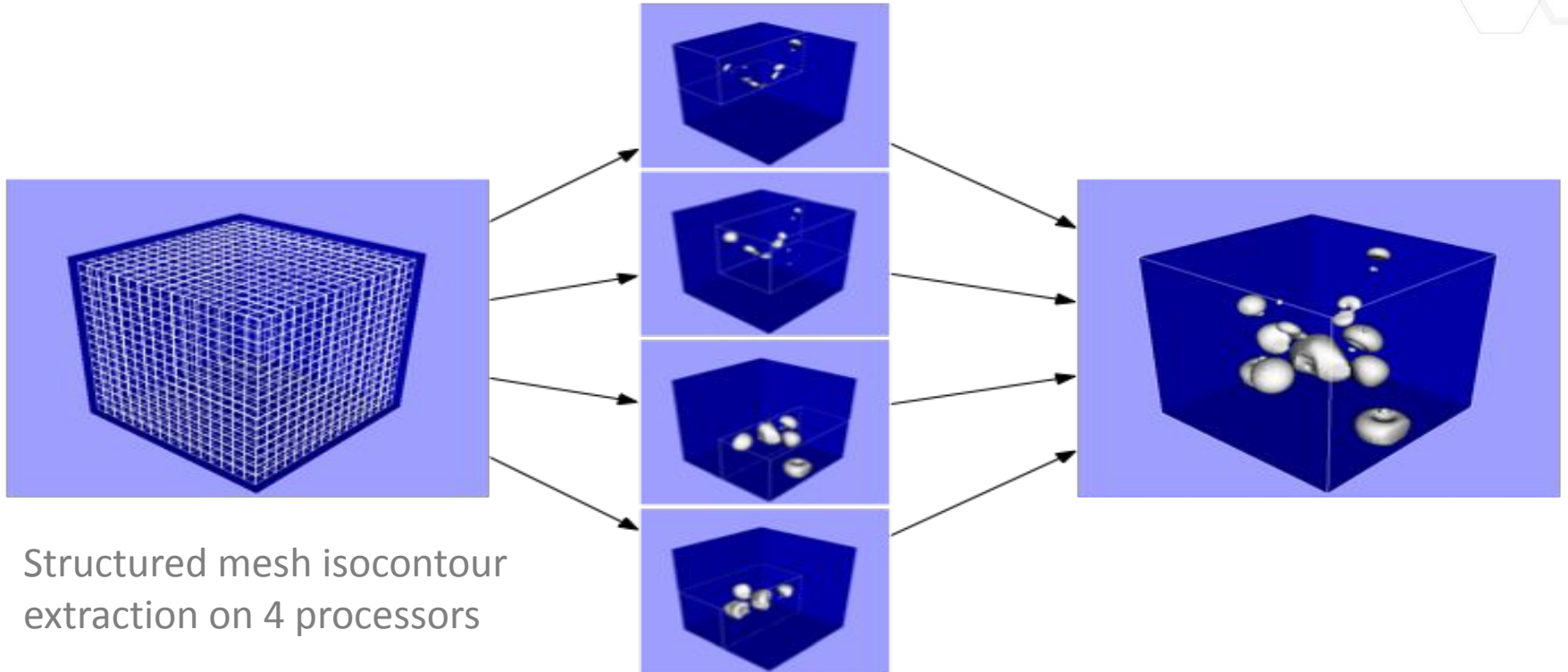
Graphic Nodes  
data/render server



In Situ  
catalyst



# ParaView: Distributed Processing of the data

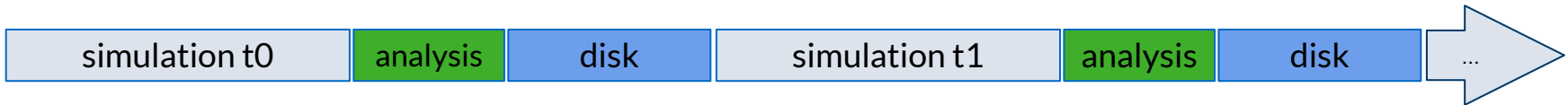


Structured mesh isocontour  
extraction on 4 processors

# In-situ analysis, with Paraview Catalyst



- **Concurrent** analysis and visualization tasks during simulation
  - Reduce I/O
  - Increase value of stored data
  - Zero-copy analysis
  - Visualization or data reduction can be done at up to each timestep (highly configurable through Python scripting and GUI)

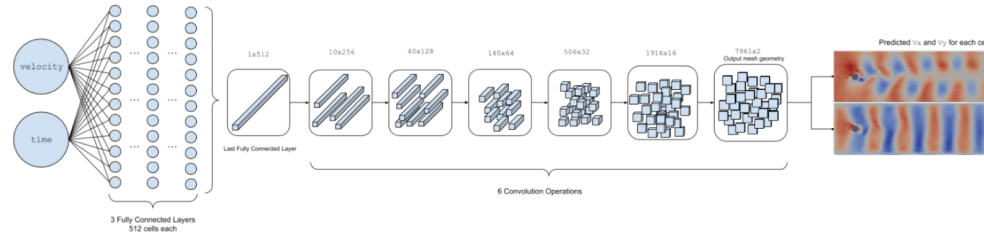


# Deep Learning in Paraview

- Goal : Mimic the behavior of a CFD simulation with deep learning to accelerate it (based on EDF's [Code Saturne](#) CFD solver)
- Rendered as it learns in paraview ( results and training monitoring)

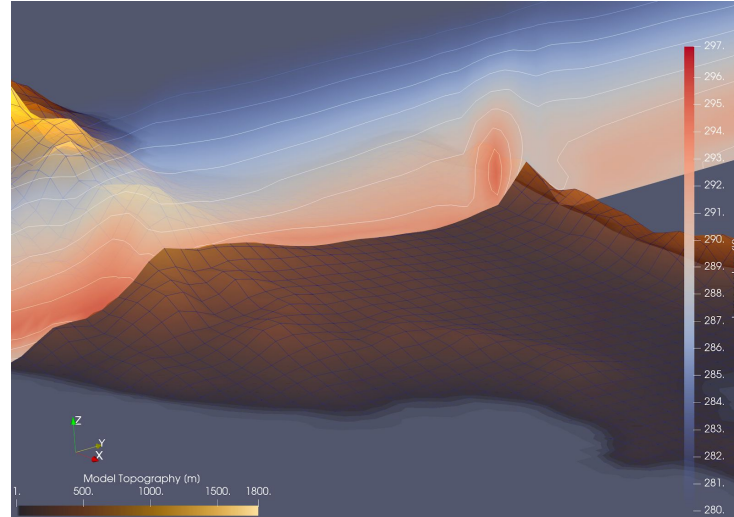
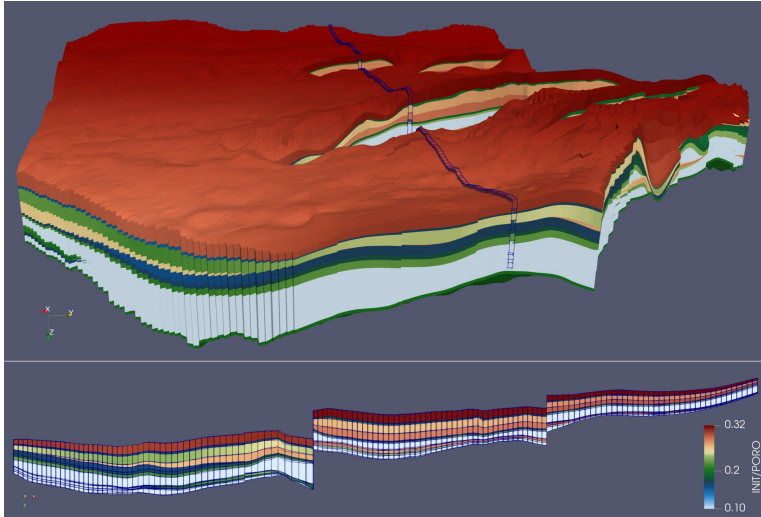
Kàrmàn Vortex  
Street surrogate  
model build with

 PyTorch



<https://www.kitware.com/deep-learning-surrogate-models-in-paraview-viewing-inference-results-and-monitoring-the-training-process-in-real-time-with-catalyst/>

# Some examples of scaled rendering

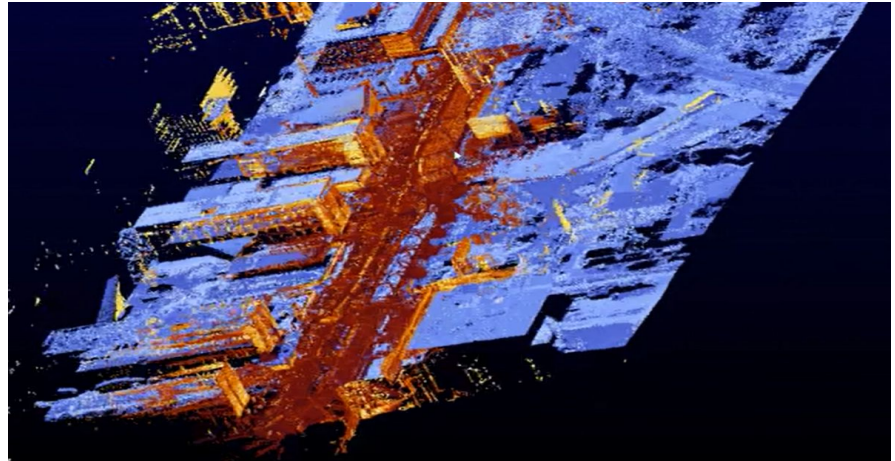


# Applications for Aerial LiDAR processing



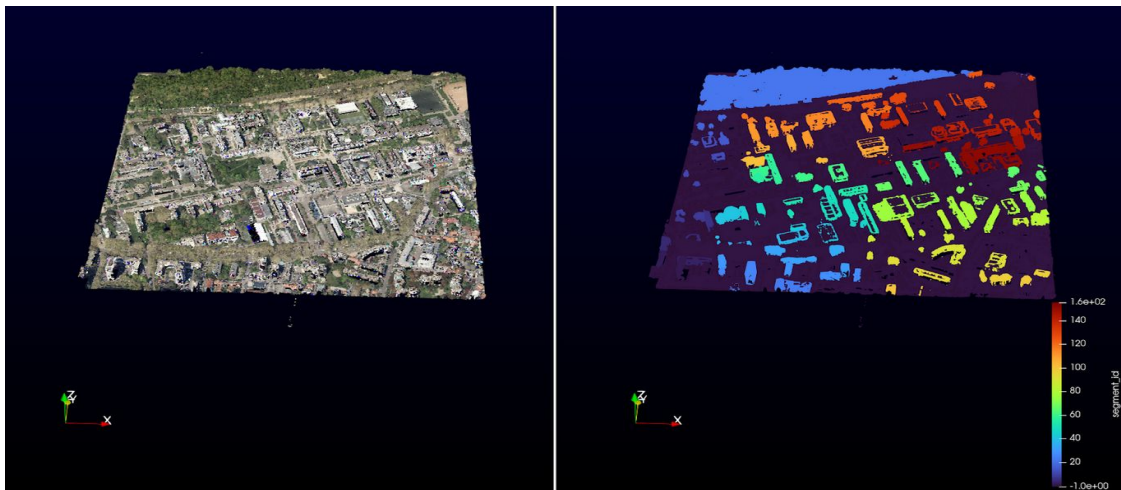
# Perspective applications for Aerial LiDAR processing : Multimodal point cloud analysis

- Run SLAM algorithm to aggregate map from the ground ( potentially colorized )
- Register it to aerial point cloud ( based on initial guess from GPS coordinate, refined with ICP like methods)



# Perspective applications for Aerial LiDAR processing : Unsupervised segmentation and automatic dimension extraction

Use Unsupervised segmentation method on massive data and Extract metrics for each georeferenced object



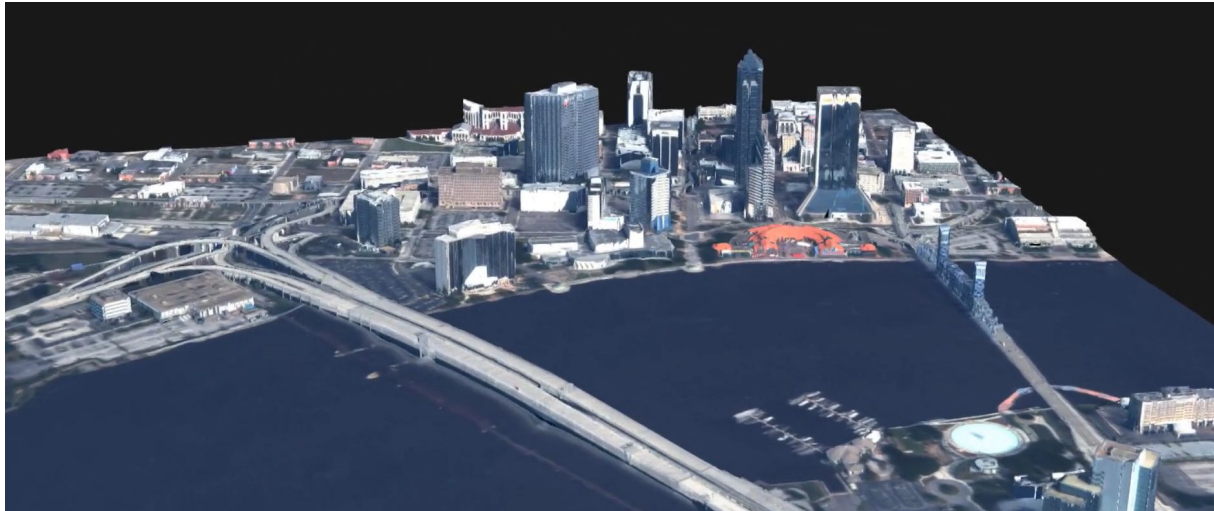
Left :  
RGB visualization in LidarView of las  
from provided by Grand Lyon ( as of  
2018 )

Right :  
Visualization of Segment-lidar (  
based on Meta's Segment Anything )  
results, from  
<https://github.com/Yarroudh/segment-lidar>



# Perspective applications for Aerial LiDAR processing : Merge with photogrammetry based models

Use lidar scans to improve photogrammetry based reconstruction accuracy



Credits : <https://www.kitware.com/3d-reconstruction-from-satellite-images/>

# ParaView

## Take Part in the First ParaView User Day Europe! Lyon, France - September 19th, 2023

- Inspiring keynotes
- Lightning talks by users
- Kitware one-to-one hands-on sessions
- Demo space
- ParaView dinner (optional)

Join the experience and present!

We understand the value of your expertise, if you want to share with the community, you can submit a presentation title and summary to present during the event.





# Thank You!



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